THERMAL IMPEDANCE AT THE INTERFACE OF CONTACTING BODIES: 1-D Example Solved by Semi-Derivatives

by

Jordan Hristov
Department of Chemical Engineering, University of Chemical Technology and Metallurgy, Sofia, Bulgaria

Original scientific paper
DOI: 10.2298/TSCI111125017H

Simple 1-D semi-infinite heat conduction problems enable to demonstrate the potential of the fractional calculus in determination of transient thermal impedances of two bodies with different initial temperatures contacting at the interface \((x = 0)\) at \(t = 0\). The approach is purely analytic and uses only semi-derivatives (half-time) and semi-integrals in the Riemann-Liouville sense. The example solved clearly reveals that the fractional calculus is more effective in calculation the thermal resistances than the entire domain solutions.

Key words: thermal impedance, fractional calculus, half-time fractional derivatives

Introduction

A thermal heating of a half-space is a general academic formulation of high temperature source interaction with materials in the material processing, precision manufacturing, and electronic devices. Although this is a very old subject \([1, 2]\), it remains scientifically important and at the microscopic scale, difficult to master in some configurations \([3]\). This particularly pertains to transient heat problems with convection, cooling of electronic devices both at the package and system level, and cooling of power semi-conductors using heat sinks \([4]\). The main problem emerging under such circumstances is in determining the material behavior in transient regime and the heat spreading in depth of the processed materials \([2, 5]\). In many cases, the time-dependent behaviour relevant to the thermal impedance is of primary importance \([5, 6]\). Some works on transient temperature field due to heat spots with uniform \([3]\) or continuous or time-dependent heat sources \([7]\) have been developed. The thermal impedance has been estimated by either exact analytical solution \([5, 7-9]\), numerical solutions \([5]\).

The present work demonstrates a straightforward solution to the transient thermal resistance of contacting bodies by half-time fractional derivatives which are not local \([10]\) but al-

* Author's e-mail: jordan.hristov@mail.bg
owing to express by single relationship the function values and the gradients. Its wide applications to transient rheology [11, 12], heat [6, 9], and mass transfer [13, 14], non-linear diffusion in porous and granular media [15], Stefan problem [16-18] manifest this technique as a power tool for efficient engineering solutions of complex problems.

**Problem statement**

Consider the heat diffusion equations of two 1-D bodies with different temperatures prior to the contact (at \( t = 0 \)), namely:

\[
\frac{\partial T_1}{\partial t} = \alpha_1 \frac{\partial^2 T_1}{\partial x^2}, \quad -\infty < x \leq 0
\]  

\[
\frac{\partial T_2}{\partial t} = \alpha_2 \frac{\partial^2 T_2}{\partial x^2}, \quad 0 < x \leq -\infty, \quad 0 < t < \infty
\]

with boundary conditions:

\[
T_{1m} = T_{10}, \quad T_{2m} = T_{20}, \quad \lambda_1 \left. \frac{\partial T_1}{\partial x} \right|_{x=-0} = \lambda_2 \left. \frac{\partial T_2}{\partial x} \right|_{x=0}
\]

(3a,b,c)

and initial conditions at the interface of mechanical contact:

\[
T = T_{10} > 0, \quad x < 0; \quad T = T_{20}, \quad x > 0; \quad T_{10} > T_{20}
\]

(3d)

We are looking for the surface thermal resistance of both bodies. The thermal impedance of the heated body is defined by the ratio \( Z = [T_2(t) - T_{2m}] / q_s(t) \), where \( q_s(t) = -\lambda_2 (\partial T_2 / \partial x) |_{x=0} \).

\[
Z = \frac{T_2(t) - T_{2m}}{q_s(t)}, \quad \text{where} \quad q_s(t) = -\lambda_2 \left. \left( \frac{\partial T_2}{\partial x} \right) \right|_{x=0}
\]

(4a, b)

The method developed in the next section demonstrates how using fractional calculus both the nominator and the denominator of (4a) can be determined (at \( x = 0 \) without developing entire domain analytical solutions.

**Solutions**

**Fractional calculus approach**

Transforming the variables as \( \Theta_1 = T_{10} - T_1 \) the heat transfer eq. (1) for the hot body is transformed into:

\[
\frac{\partial \Theta_1}{\partial t} = \alpha_1 \frac{\partial^2 \Theta_1}{\partial x^2}, \quad \Theta(x = -\infty) = 0, \quad \Theta(t = 0) = 0, \quad x < 0
\]

(5)

At the surface \( x = 0 \) the temperature and the heat flux are related as [9, 19] \( (\partial \Theta_1 / \partial x)|_{x=0} = (1/\alpha_1^{1/2}) D_1^{1/2} \Theta_1 \), and substituting \( \Theta_1 = T_{10} - T_1 \) we have:

\[
\left. \frac{\partial T_1}{\partial x} \right|_{x=0} = \frac{1}{\sqrt{\alpha_1}} \left( D_1^{1/2} T_s - T_{10} \right), \quad x = 0, \quad q_{1(x=0)} = -\lambda_1 \left. \frac{\partial T_1}{\partial x} \right|_{x=0}
\]

(6a,b)

Similarly, for the cold body \( (x > 0, T_m = T_{20}) \), and \( \Theta_2 = T_2 - T_{20} \), we have:
\[
\frac{\partial T_s}{\partial x} \bigg|_{x=0} = \frac{1}{\sqrt{\lambda_2}} \left( D_1^{1/2} T_s - \frac{T_{10}}{\sqrt{\pi t}} \right); \quad q_{2(x+0)} = -\lambda_2 \frac{\partial T_s}{\partial x} \bigg|_{x=+0} \quad (7)
\]

Equating the heat fluxes of both bodies at \(x = 0\) and integrating with respect to the time \(t\), we get:
\[
D_1^{1/2} T_s = \frac{1}{\sqrt{\pi t}} \frac{\lambda_1 \sqrt{\alpha_2} T_{10} - \lambda_2 \sqrt{\alpha_1} T_{20}}{\lambda_1 \sqrt{\alpha_2} + \lambda_2 \sqrt{\alpha_1}}; \quad T_s = \frac{\lambda_1 \sqrt{\alpha_2} T_{10} - \lambda_2 \sqrt{\alpha_1} T_{20}}{\lambda_1 \sqrt{\alpha_2} + \lambda_2 \sqrt{\alpha_1}} \quad (8a,b)
\]

If the initial temperature of the cold body is assumed zero, i.e., \(T_{20} = 0\) that is equivalent to a shift of the temperature scale origin, then we get the result of Babenko [19]:
\[
D_1^{1/2} T_s = \frac{T_{10}}{\sqrt{\pi t}} \frac{\lambda_1 \sqrt{\alpha_2}}{\lambda_1 \sqrt{\alpha_2} + \lambda_2 \sqrt{\alpha_1}}; \quad T_s = \frac{\lambda_1 \sqrt{\alpha_2} T_{10} - \lambda_2 \sqrt{\alpha_1} T_{20}}{\lambda_1 \sqrt{\alpha_2} + \lambda_2 \sqrt{\alpha_1}} \quad (9a,b)
\]

For seek for simplicity, we will assume hereafter that \(T_{20} = 0\). Then, the heat flux across the contact interface is defined by eq. (7), namely:
\[
q_s = -\lambda_2 \frac{\partial T_s}{\partial x} \bigg|_{x=+0} = \frac{\lambda_2}{\sqrt{\alpha_2}} D_1^{1/2} T_s = \frac{T_{10}}{\sqrt{\pi t}} \frac{\lambda_1 \lambda_2}{\lambda_1 \sqrt{\alpha_1} + \lambda_2 \sqrt{\alpha_1}} \quad (10)
\]

Then, the thermal impedance of the heated cold body \((\alpha > 0, T = 0)\) is \(Z_2 = T_s/q_s = (\pi t)^{1/2}(\alpha_2 t)^{1/2} \lambda_2\) or \(Z_2 = (\pi t)^{1/2}(\epsilon_2)^{1/2} \), where \(\epsilon = (\rho C_p)_{\text{m}}^{1/2}\) is the material heat effusivity.

Similarly, with respect to the chilled body \((\alpha < 0, T_1 = T_{10})\) we get:
\[
q_{sl} = -\lambda_1 \frac{\partial T_s}{\partial x} \bigg|_{x=0} = -\frac{\lambda_1}{\sqrt{\alpha_1}} \left( D_1^{1/2} T_s - \frac{T_{10}}{\sqrt{\pi t}} \right) = \frac{T_{10}}{\sqrt{\pi t}} \frac{\lambda_1 \lambda_2}{\lambda_1 \sqrt{\alpha_1} + \lambda_2 \sqrt{\alpha_1}} \quad (11)
\]

\[
Z_1 = \frac{T_s - T_{10}}{q_{sl}} = \frac{\sqrt{\alpha_1} t}{\sqrt{\alpha_1}}; \quad Z_1 = \frac{\sqrt{\pi t}}{\sqrt{\epsilon_1}} \quad (12a, b)
\]

**Comparative classical solutions**

The exact solution of the temperature field of both bodies is [20]:
\[
T_1 (x, t) = T_{10} - \frac{T_{10} - T_{20}}{1 + K_1} \text{erfc} \left( -\frac{x}{2\sqrt{\alpha_1} t} \right); \quad T_2 (x, t) = T_{20} - \frac{T_{10} - T_{20}}{1 + K_2} \text{erfc} \left( -\frac{x}{2\sqrt{\alpha_2} t} \right) \quad (13a, b)
\]

where
\[
K_1 = \frac{\lambda_1 C_p \rho_1}{\sqrt{\lambda_2 C_p \rho_2}} = \frac{\epsilon_1}{\epsilon_2}; \quad K_2 = \frac{1}{K_1} \quad (14a,b)
\]

At \(x = 0\) we get:
\[
T_1 (0, t) = T_{10} - \frac{T_{10} - T_{20}}{1 + K_1}; \quad T_2 (0, t) = T_{20} + \frac{T_{10} - T_{20}}{1 + K_2} \quad (15a,b)
\]

\[
\lambda_1 \frac{\partial T_1 (0, t)}{\partial x} = \lambda_1 \frac{T_{10} - T_{20}}{1 + K_1} \left( \frac{1}{\sqrt{\pi \sqrt{\alpha_1}} t} \right); \quad \lambda_2 \frac{\partial T_2 (0, t)}{\partial x} = \lambda_2 \frac{T_{10} - T_{20}}{1 + K_2} \left( \frac{1}{\sqrt{\pi \sqrt{\alpha_2}} t} \right) \quad (16a, b)
\]
Hence,

\[ Z_1 = \sqrt{\pi} \frac{\sqrt{\lambda_1 t}}{\sqrt{\sigma_1}} = \frac{\sqrt{\pi}}{\sqrt{\lambda_1}}; \quad Z_2 = \sqrt{\pi} \frac{\sqrt{\lambda_2 t}}{\sqrt{\sigma_2}} = \frac{\sqrt{\pi}}{\sqrt{\lambda_2}} \]  

(17a, b)

Comments

The method developed here shows direct links between two interrelated issues required to calculate the transient thermal impedance of heated bodies: surface temperatures and fluxes. The common approach is to develop the entire domain solutions through time-wasting techniques, special function, etc., which finally reduce to only pre-factors depending on the imposed boundary conditions when the space co-ordinate equals to zero. The 1-D problem were especially chosen to demonstrate the approach because such problem are classic in the literature and in many cases either exact or approximate solutions exist. Moreover, it can be a good approximation to real physical problems where heat is transfer by short time contacts such as fluidized bed with immersed surfaces, wearing of sliding parts, safety problems with hot machine elements, etc. All results were especially presented as products of \((\alpha t)^{1/2}\) \([\text{K}/\text{Wm}^2]\) or the effusivity \(\varepsilon = (\rho \lambda C_p)^{1/2}\), and terms depending on the type of the imposed boundary condition, as in the classical problems employing entire domain solutions. Cases of 1-D bodies with finite lengths can be also solved by the fractional calculus approach but this needs different techniques beyond the scope of the present work.

Conclusions

The article presents a method for estimation and calculation of transient thermal impedances of 1-D semi-infinite areas (bodies) when they contact \(t = 0\) at the interface \(x = 0\). The method is based on relationships based on Riemann-Liouville half-time fractional derivatives and integrals relating both the temperature and the heat flux at any point of the domain. The approach is simple and avoids development of entire-domain solutions.

Nomenclature

\( C_p \) – specific heat capacity, \([\text{Jkg}^{-1}]\)
\( q_{s1} \) – surface flux density of the hot body, \([\text{Wm}^{-2}]\)
\( q_{s2} \) – surface flux density of the cold body, \([\text{Wm}^{-2}]\)
\( T \) – temperature, \([\text{K}]\)
\( T_s \) – surface temperature (at the contact interface), \([\text{K}]\)
\( T_{10} - T_{20} \) – temperature of both bodies far a way from the contacting surface (undisturbed temperature fields), \([\text{K}]\)
\( T_{1b} - T_{2b} \) – boundary conditions at the contacting interface, \([\text{K}]\)
\( t \) – time, \([\text{s}]\)
\( x \) – space co-ordinate, \([\text{m}]\)
\( Z \) – thermal impedance (see the definition by eq. 4a), \([\text{KW}^{-2}\text{m}^{-1}]\)
\( z \) – dummy variable in the definition of the Riemann-Liouville (RL) fractional derivative, \([\text{-}]\)
\( R_L \frac{\partial^{1/2} T(x,t)}{\partial x^{1/2}} = \frac{[1/\Gamma(1/2)]d}{dx} \int_0^T (x-z)^{1/2} dz \)
– time-fractional semi-derivative of the Riemann-Liouville (RL) sense
\( \alpha \) – thermal diffusivity, \([\text{m}^2\text{s}^{-1}]\)
\( \Gamma \) – gamma function
\( \varepsilon \) – effusivity \((= \rho \lambda C_p)^{1/2}\), \([\text{Jm}^{-2}\text{s}^{0.5}]\)
\( \lambda \) – heat conductivity, \([\text{Wm}^{-2}\text{K}^{-1}]\)
\( \rho \) – density, \([\text{kgm}^{-3}]\)

Greek symbols

\( \alpha \) – thermal diffusivity, \([\text{m}^2\text{s}^{-1}]\)
\( \Gamma \) – gamma function
\( \varepsilon \) – effusivity \((= \rho \lambda C_p)^{1/2}\), \([\text{Jm}^{-2}\text{s}^{0.5}]\)
\( \lambda \) – heat conductivity, \([\text{Wm}^{-2}\text{K}^{-1}]\)
\( \rho \) – density, \([\text{kgm}^{-3}]\)

Subscripts

1 – hot body
2 – cold body
References